

# Utilizing UAS in of support NOAA river ice breakup forecasting in Alaska

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## River forecasting background of ice conditions in Alaska and events

- NOAA UAS River Forecasting Workshop (2/2012)
- Galena flood (5/2013)
- NOAA UAS Arctic and River Forecasting Workshop (9/2014)
- Alaska Center for UAS (ACUASI) deployed to Circle (4/2016).



Galena on the bank of the Yukon River



Galena flood



### The reports recommendations regarding river break-up

- NOAA 1<sup>st</sup> workshop data requirements:
  - Ice flow- size, motion- near real-time
  - Ice Jams height in near real time
  - Water Inundation /flooding
  - Jam location, thickness, height
- NOAA 2<sup>nd</sup> workshop
  - Lack of data (Carven Scott)
    - Cover an area that is 20 times larger that average NWS in the lower 48
    - Very sparse precipitation and river gauges in Alaska
    - Need real time data
  - In the case of an ice jam
    - Height of ice jam
    - Longitudinal extent of ice jam
    - Water height above and below the ice jam
  - Requirements for UAS River ice information , channel ice conditions, ice movement, ice structure, ice jams



## Alaska Hydrology UAS requirements

- Geophysical questions related to river ice
  - General ice condition along the river
  - Location of breakup front
  - Presence and severity of current flooding
  - Ice integrity
  - Locations of strain and stress
- Community reconnaissance (+/- 20 miles above and bellow the town)

\*\*Galena flood



## Alaska Hydrology UAS requirements

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- DEM around villages for better flood modeling



## Spring breakup timeline

- Mission overview (April 5) Yukon rive at Circle
  - 1. On the road system
  - 2. NWS/DHSEM river-watch team fly that stretch
  - 3. Compliment large fix wing mapping by Dr. Jessica Cherry
  - 4. Circle has experienced flooding due to ice jams in the past.
  - 5. Yukon river is wide an adequate to compare with new satellite data sets
  - Alaska Center for UAS Integration (ACUASI): deployed fix wing and rotor craft
    - Maximum endurance of about 40 minutes
    - Maximum cruising velocity 33 mph
    - Potential of total distance to cover 20 miles
    - <u>But-FAA limitation to UAS within line of sight ≈2 miles</u>
  - Proposed schedule
    - Budget enabled about three operation days
    - Breakup running 1-2 weeks early (average May 10, earliest April 30)
    - Five days notice (from the time ice breaks in Eagle)



## Continue

- Data collection requirements:
  - Multiple sensor Infrared
  - Visible- orthomosaic and DEM (structure from Motion)
  - Multiple flights over several days are important to NWS to get a time series of data and observe differential changes in ice conditions.
  - NWS interested in observing pre-breakup signatures (thermal and elevation changes) that are directly related to ice movement (breakup), to improve lead time for forecasting ice breakup, and ultimately ice jams and ultimately flooding.
  - Would to like to improve DEM of the Circle area for flood prediction



## Supporting Aircrafts

- Responder-
  - Single rotor electrical craft
  - Payload several pounds
  - Cruising speed 30 mph
  - Endurance 40 min
- Aeromapper
  - Fix wing
  - Payload: Close to a pound
  - Cruising speed 30 mph
  - Endurance 40 min







## Continue chronology

• Defining Area of Interest (AOI) About 3X3 square miles





## Mission Spread Sheet

	Х	Y	Toal pixels	;	Transects			
Number of pixels ir	6000	4000	24000000		Long side transect width	70.10 m	70.10	
Size of the sensor	23	16.5	mm	(Wiki)	# of transects	68.87 n	<u>68.87</u>	
Size of the pixel	3.833333	4.125	μm					
Focal Length	24	24	mm		Flight Profile			
					Velocity	55.00 Km/h		
					Velocity	916.67 meter/min		
Field of view					Velocity	15.28 m/s		
At altitude	121.92	meters			Velocity	34.375 mph		
Altitude in feet	400	Ft			Total flight path (n transsects+1	342162.21 m		
Field Of View	51.20438	37.94082	0		Total Flight path	342.16 Km		116 m
					Mission duration (based on airc	373.27 minutes		0.116
Foot print	116.84	83.82	m		Camera intervelometer			0.0725
Foot print	38.94667	27.94	ft		Inetervelometer (often we choo	2 sec		
pixels/m	34.23485	71.58196			Advance during one lapse ( base	16.76 m		
Centimeters/pixel	2.921	1.397			Maximum V	8.38 m/s		
#pixels per square	2450.60					30.1752 km/hr		
AOI						18.8595 mph		
Length	3	miles	4828.044	m				
Width	3	miles	4828.044	m	Data size			
Area	9	Mile^2	23.30978	Km^2	Number of pictures	11198.04		
Overlap								
Froward Overlap	0.8	Y						
Side overlap	0.6	Х						

## Continue chronology

- Defining Area of Interest (AOI) About 3X3 square miles
- Break down the AOI into three AOI : 2 X0.25 square miles
  - Priority 1
  - Priority 2
  - Priority 3





## Sequence of events

- April 22 Break up in Dawson
- April 24, 8 pm Ice broke in Eagle
- April 26, Mission readiness and deploy within 48 hr.
- April 28, 8:00 am departed UAF (Fairbanks)
  - 12:00 stuck be a flooded road section
  - 15:00 reach Circle
  - 18:00 Flight priority 1
- April 29
  - Morning fly priority 2
  - Noon fly priority 2
  - Evening fly priority 2 -about an hour after landing the ice broke



## **ERMA** server host



#### ALASKA

#### **ERMA** server host

## Plotting some of the data on ERMA



## Ice blocks point cloud





## Ice Blocks Point Cloud





## VIIRS data products (Dr. Sanmei Li)

Eagle Flood Map: 04/24/16 Fortymile Dawson iver Flood: Alaska



## Responder surveying the Yukon river ice





## Working closely with local school





## Notes and conclusion

- ACUASI deployed within 48 hours- aircraft was in the air within 60 hours
- Data was provided to ERMA almost real time (<60 min from landing)
- For each discussed scenario, in the NOAA reports, research and practice need to take place in order to be effective in responding to a disaster (NSF, Homeland Security)
- Future missions should be deployed at similar altitude to manned airborne
- Motion Video- Although motion video is making large strides into a useful geospatial tool. The file is often big, requires human interpretation, and hard to compare two data sets of different time.
- Data products such as the ice/liquid by are often very compact and the easiest to send under poor communication protocol.
  - Perhaps ACUASI find a grant to develop a small payload to produce similar data product to the VIIRS data set
- A report is in the work(comparison to the SUOMI VIIRS ice/water product)



## Special Thanks

- Robbie Hood and John Coffey (JC) for the support in developing UAS support in Arctic and river monitoring.
- Circle School
- ACUASI engineering and logistical support
- The university of Alaska Fairbanks and the Geophysical Institute



## Reference

• UAS RFC Workshop Summary final

https://drive.google.com/open?id=0B6vqMOQTeLkIZVFQV21Se mJWSTFrUnUtYk90QWIoNDRiVU9v

• UAS RFC Workshop II Report

<u>https://drive.google.com/open?id=0B6vqMOQTeLkINkxi</u> <u>MDRhcnJ1UU9vdUJJRIBhTIdjZWFPNG9N</u>

