

NOAA's Marine and Arctic Monitoring UAS strategies

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NOAA sUAS



Overview

- NOAA UAS Program A Brief History
- sUAS for Marine Resource Monitoring, Arctic and Emergency Operations
- Successes and Challenges
- Looking Forward
- Questions



NOAA Requirements for UAS



Missions that are:

- Dirty
- Dull
- Dangerous (Threat assessments)
- Denied or Impossible to get to and/or impossible to use a manned aircraft (Low ceilings, etc.):
 - Remote
 - Unique mission requirements:
 - Smaller and <u>quieter</u> UAS don't disturb animals as much as a manned aircraft would
 - Stealth provides advantages for surveillance and enforcement
 - o Persistence
 - Better data resolution
 - $\circ\,$ Can be quickly deployed and positioned

NOAA and UAS





Altair at Channel Islands

•Global Hawk



NASA Global Hawk Operations Center





NOAA / NASA Altair Test Flight Crew





NOAA and UAS





- NASA Ikhana
- ScanEagle
- Manta







- NOAA tests various systems including ScanEagle in 2007 and 2009 and acquires two multi-copters in 2010 and two Puma UAS in 2011
- Development of protocols and procedures
- Missions:
 - Living Marine Resource Surveys
 - Habitat Mapping and Characterization
 - Enforcement
 - Emergency Response
 - Marine Debris
 - USCG Arctic Support



Scan Eagle on test deployment in Puget Sound 2007







Scan Eagle recovery at sea



Multi-copters





Md4-1000

Issues with orientation and magnetometers
No "waterproof" equipment available yet
Some priced low enough to be "expendable"
The enabling technology is battery power



PUMA AE System







The "holy grail": Launching and recovering at sea



AV GCS/RVT on R/V Shearwater







Data distribution architecture

ND ATMOSP





Blue Whale Tagging Support





Living Marine Resource Surveys

Seabird Surveys





Living Marine Resource Surveys

• Pinnipeds

NDAA

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Enforcement



2012-08-30_07-59-16.00Z 11S KT 50470 60999 Alt: 336 ft MSL True Heading: 126°



CFOV Heading: 31° CFOV Position: 11S KT 50546 61077 CFOV Alt: 3 ft MSL

FOV Corner Positions: UL: 11S KT 50535 61123 UR: 11S KT 50606 61098 LR: 11S KT 50554 61042 LL: 11S KT 50509 61063



Simulated seal and turtle





ormeat Flant Rug: 99 m Flow Haly: 326° FFOV Haly: 326° 39.362° W 158° 10.348° FFOV Lat/Lon: N 21° 39.362° W 158° 10.348°

ligiN Lat/Lon: N 21° 38.957′ № 158° 10.518′ NNOE → HOME: 0.1 km SARING → HOME: 131° IND SEEED: 16.5 kts IND DEE: 84°

Hawaii Marine Debris testing 6/12





2012-06-20 21:06:10Z Lat/Lon: N 21° 39.092' W 158° 10.676' Alt: 344 ft MSL Mag: 36°



Gimbal FOV Data: Slant Rng: 184 m CFOV Hdg: 339° CFOV Lat/Lon: N 21° 39.203' W 158° 10.720' Horiz. FOV: 6.3°

ORIGIN Lat/Lon: N 21° 39.386' W 158° 10.509' RANGE -> HOME: 0.1 km BEARING -> HOME: 176° WIND SPEED: 00.0 kts WIND DIR: 68°

Emergency Response & Oil Spill Simulation





Coast Guard UAS partnership study of oil spill monitoring in Santa Barbara channel



Lat/Lon: N 33° 48' 31.53" W 119° 46' 18.60" Alt: 351 ft MSL Mag: 39°



Gimbal FOV Data: Slant Rng: 259 m CFOV Hdg: 320° CFOV Lat/Lon: N 33° 48' 37.61" W 119° 46' 23.82" Horiz. FOV: 29.6°

Targeting Data: Target S Lat/Lon: N 33° 48' 36.66" W 119° 46' 26.12" Target T Lat/Lon: N 33° 48' 39.29" W 119° 46' 23.45" ADD 94 m RIGHT 48 m Range: 106 m Mag Bearing: 27°

Hawaii Activities





362,073 square kilometers of the Pacific Ocean



Puma Vessel Operations

















Trig Island, Puma Flight 14-006 19 June 2014, 1102L



2014_06_19_21_02_39_3QUG73564056 -File Size: 1.74 MB (1,828,802 bytes) -Dimensions: 2592 x 1944 Pixels -Resolution: 96 x 96 dpi -Bit Depth: 24 (16777216 colors – 256 each RGB)

> Unofficial Species Counts Monk Seals: about 20 Mother-Pup Pairs: about 6 Turtles on Beach: about 200 Turtles in Water: about 40 Birds: about 200

* Derived from multiple images and video



Trig Island, Puma Flight 14-006 19 June 2014, 1110L





Flight 14-006, 19 Jun 2014, 1110L Image 2014_06_19_21_10_58_3QUG73594061 Left half of image Trig Island, Puma Flight 14-006 19 June 2014, 1148L





Flight 14-006, 19 Jun 2014, 1148L Image 2014_06_19_21_48_42_3QUG72424081 Float in center of image

Best Image of a Mother-Pup Monk Seal Pair





Flight 14-006, 19 Jun 2014, 1108L Image 2014_06_19_21_10_58_3QUG73594061 Closest edge of image

Turtle Counts, Morphology, Activity





Flight 14-006, 19 Jun 2014, 1108L Image 2014_06_19_21_08_47_3QUG7349406 8 Edges, lower half of image





Tern Island Birds and Vegetation



Flight 14-006, 19 Jun 2014, 1206L Image 2014_06_20_04_05_58_3QUG69674057 Left edge of image



EO to IR Comparison

2014-06-20_04-40-01.00Z 03Q UG 68978 40306 Alt: 265 ft MSL True Heading: 83°



Flight 14-008, 19 Jun 2014, 1840L Image 2014_06_20_04_05_58_3QUG69674057 Entire image



CFOV Heading: 46° CFOV Position: 03Q UG 69204 40447 CFOV Alt: 0 ft MSL

FOV Corner Positions: UL: 03Q UG 69211 4055 UR: 03Q UG 69408 4048 Flight 14-008, 19 Jun 2014, 1840L Image 2014_06_20_04_05_58_3QUG69674057 Entire image





Launch and recovery at sea





Arctic Support





Operation Arctic Shield 2013 & 2014

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ND ATMOS

NOAA

NOAA USCG Healy Deployment, Operational and Scientific Goals



- ✓ Water and Ice Landings
- ✓ Deck Landing
- ✓ Net Capture System
- Conduct Intelligence, Surveillance, and Reconnaissance (ISR) Operations Stream Full Motion Video (FMV), EO and IR from Puma AE for
 - \checkmark Detection and monitoring of oil spilled from ship or oil exploration
 - ✓ Detection and monitoring of marine debris from ship
 - ✓ Sea ice ridge detection/monitoring
 - ✓ Usefulness in search and rescue (emergency response) scenarios
 - ✓ Marine and marine mammal monitoring (opportunistically)
 - ✓ Producing a Digital Elevation Map (DEM) of ice ridge and surrounding area
 - Preparation for future boundary layer research from sUAS



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- Utilize the Environmental Response Management Application (ERMA)
- ✓ Coordinate with ONR Marginal Ice Zone Experiment (MIZOPEX) FY14
- ✓ Coordinate with the UAF for ScanEagle flight operations coordination and data exchange
- ✓ Coordinate with the NOAA NMFS Manned Marine Mammal Survey Flights

Puma "Due Regard" Ops & Recovery Testing



✓ Due Regard Operations
 ✓ Water and Ice Landings
 ✓ Deck Landing
 ✓ Net Capture System





ISR Missions including Oil Spill & SAR

✓ Sea ice ridge detection/monitoring
 ✓ Usefulness in search and rescue
 scenarios

Detection and monitoring of oil spilled from ship

 \checkmark Detection and monitoring of marine debris

Lat/Lon: N 73° 58' 14.84" W 155° 03' 20.64" Alt: 266 ft MSL Mag: 241°



Gimbal FOV Data: Slant Rng: 159 m CFOV Hdg: 181° CFOV Lat/Lon: N 73° 58' 13.34" W 155° 03' 20.81" Horiz. FOV: 29.6°







ERMA Coordination



- ERMA® is an online mapping tool that integrates both static and real-time data, such as Environmental Sensitivity Index (ESI) maps, ship locations, weather, and ocean currents, in a centralized, easy-to-use format for environmental responders and decision makers. ERMA enables a user to quickly and securely upload, manipulate, export, and display spatial data in a Geographic Information System (GIS) map.
- Second year participations through the UAS Program.
- Software demonstration/ test with 2d3



Software and Datasets

•<u>ADIOS</u>, oil weathering model.

• ERMA[®], online mapping tool for environmental response data, adapted to a variety of regions.

•<u>GNOME</u>, oil spill trajectory model.

•<u>GOODS</u>, a tool that helps GNOME users access base maps, ocean currents, and winds.

•<u>NUCOS</u>, a unit converter that includes units unique to oil spill response.

•<u>Spill Tools</u>, a set of three programs: the Mechanical Equipment Calculator, the In Situ Burn Calculator, and the Dispersant Mission Planner.

•<u>Trajectory Analysis Planner</u>, oil spill contingency planning software. •<u>Environmental Sensitivity Index (ESI) maps and data</u>, concise summaries of coastal resources that may be at risk in a spill incident.

Arctic Shield Take Aways & Operational Assessment



- Arctic is a Challenging Environment
 - Platform flight envelope must be expanded
 - Platform recovery process and sensors must continue to be improved
 - "Due Regard" operations must be expanded
- Partnerships are crucial (Maritime Strategy)
 - People, property and platforms (data captured) are valuable
 - Must maximize operations and data sharing opportunities







PARTMENT

- **Durabity:** Puma is tough and not overly complicated to repair and maintain. It takes a fair amount of abuse
- Adaptability: Puma's ability to be operated in all environments (as long as it isn't too rainy or windy...)
- **Transportability** and ability to be carried aboard, without modifications to the vessels
- Airworthyness documentation
- Spares and support
- •Great support from AeroVironment

sUAS requirements for NOAA's maritime and Arctic use



- High resolution optical and infrared imagery
- Additional payloads:
 - •Nadir mapping cameras
 - •LiDAR
 - Multispectral
- Simple, non-proprietary interfaces to quickly ingest data into GIS systems
- Ability to tap into high resolution data stream with metadata in real-time and relay data to incident command centers via ship's satellite communication systems (Google Loon?)
- Ability to launch and recover aboard ship
- Ability to operate in up to 35 knots of wind
- Heated pitot tube
- Ability to sense icing or to de-ice the wings and control surfaces

The future looks bright

- Routine VLOS operations in the NAS under new FAA rules
- More equipment and sensor offerings from industry
- BVLOS operation in the Arctic and remote oceanic areas for agencies
- Emergency operations
 Enforcement
 Ghost Nets and other uniqué missions.





